

# Random surface roughening with quenched disorder and turbulent environment

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(1)

### Kardar-Parisi-Zhang model



### Renormalization group analysis

Canonical dimensions analysis shows that:

- New term <sup>1</sup>/<sub>2</sub>uh'vv must be added in order for the problem (4) to become renormalizable. There are 5 divergent Green's functions.
- All the coupling constants g<sub>0</sub> = D<sub>0</sub>/κ<sub>0</sub><sup>4</sup>, w<sub>0</sub> = B<sub>0</sub>/κ<sub>0</sub>, u become simultaneously dimensionless at d = 4 (it is a logarithmic dimension), and ε = 4 d, ξ are the expansion parameters of the perturbation theory.

Renormalized action functional ( $Z_i$  are renormalization constants) is:  $S_R(\Phi) = \frac{1}{2} Z_1 h' Dh' + h' \{ -\partial_t h - Z_5 v_i \partial_i h + Z_2 \varkappa \partial^2 h + \frac{1}{2} Z_3 (\partial h)^2 \} + S_v + Z_4 \frac{u}{2} h' v^2$ (5)

### **One-loop calculation**

- Feynman diagrams technique was used to calculate the diverging 1-irreducible Green's functions.
- All calculations were made in the leading order of (ε,ξ) expansion.
   See [5] for example of similar calculations.

(4)

**Figure 1:** Stochastic growth of a flame front and a sand seabed

• Kardar-Parisi-Zhang (KPZ) model is a well-known non-equilibrium dynamics model that describes a wide range of phenomena: random surface roughening, solidification and flame fronts, smoke and colloid aggregates, tumors, etc. [1], [2]. KPZ model is a nonlinear differential equation for the field h(x) = h(x, t) (profile height) that depends on the *d*-dimensional coordinate *x* and time *t*:

$$\partial_t h = \varkappa_0 \partial^2 h + \frac{\lambda_0}{2} (\partial h)^2 + f \tag{1}$$

Here  $\partial_t = \partial/\partial_t$ ,  $\partial_i = \partial/\partial_i$ ,  $\partial^2 = \partial_i\partial_i$ ,  $(\partial h)^2 = (\partial_i h)(\partial_i h)$ , i = 1, ..., d. Parameter  $\varkappa_0 > 0$ ;  $\lambda_0$  can be positive or negative, f is random noise.

- Let us put  $\lambda_0 = 1$  (this can be achieved by rescaling of the parameters).
- Let us choose *f* in the form

$$\langle f(x)f(x')\rangle = D_0\delta^{(d)}(x-x') \tag{2}$$

This is "spatially quenched" (time-independent) noise; experimental data [3] indicates that it better models landscape erosion than white noise. Here  $D_0$  is a positive amplitude.

### Velocity ensemble

 Turbulent motion of the environment is modelled by the Kazantsev-Kraichnan ensemble [4] that has a distribution with zero mean and the correlation function of the form

$$\langle v_i(t,x)v_j(t',x') \rangle = \delta(t-t')D_{ij}(x-x') D_{ij}(r) = B_0 \int_{k>m} \frac{dk}{(2\pi)^d k^{d+\xi}} P_{ij}(k)e^{ik_q r_q}$$
(3)

 $P_{ij}(k) = \delta_{ij} - k_i k_j / k^2$  is the transverse projector, it reflects the

## Fixed points and and critical dimensions

The long-time, large-scale asymptotic behaviour of the Green's functions is determined by the IR attractive fixed points. For field h:

$$\langle h(t, \mathbf{x}) h(0, \mathbf{0}) \rangle \simeq r^{-2\Delta_h} \mathcal{F}\left(t/r^{\Delta_\omega}\right),$$
 (6)

where  $\mathcal{F}(...)$  is a scaling function,  $\Delta_i$  are critical dimensions. ■ RG analysis reveals that there are six fixed points (x = wu):

- $g^* = x^* = w^* = 0; \Delta_{\omega} = 2, \Delta_h = 0, \Delta_v = 1 \xi/2$   $g^* = -\varepsilon, w^* = 0, x^* = 0; \Delta_{\omega} = 2 \varepsilon/4, \Delta_h = 0, \Delta_v = 1 \varepsilon/8 \xi/2$   $g^* = -2(\varepsilon + 2\xi), w^* = -4(\varepsilon + 4\xi)/3, x^* = w^*; \Delta_{\omega} = 2 + \xi, \Delta_h = 0, \Delta_v = 1 \xi$   $g^* = -2(\varepsilon 2\xi), w^* = 4(4\xi \varepsilon)/3, x^* = 4(2\xi \varepsilon)/3; \Delta_{\omega} = 2 \xi, \Delta_h = 0, \Delta_v = 1 \xi$   $g^* = 0, w^* = 0, x^* = -8\xi/3; \Delta_{\omega} = 2, \Delta_h = 0, \Delta_v = 1 \xi/2$   $g^* = -\varepsilon, w^* = 0, x^* = -8\xi/3; \Delta_{\omega} = 2 \varepsilon/4, \Delta_h = 0, \Delta_v = 1 \varepsilon/8 \xi/2$
- They become attractive at certain values of the parameters ( $\varepsilon$ ,  $\xi$ ):





#### Conclusion

KPZ equation with spatially quenched noise advected by velocity field modelled by Kazantsev-Kraichnan ensemble is non-renormalizable theory; a new term h'vv must be added in order to apply renormalization procedure (induced nonlinearity).

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- incompressibility of the fluid ( $\partial_i v_i = 0$ ),  $k = |\mathbf{k}|$  is the wave number,  $B_0 > 0$  is a positive amplitude,  $0 < \xi < 2$ . The cutoff k > m serves as an infrared (IR) regularization.
- The advection by the velocity field is realised by "minimal" replacement  $\nabla_t h = \partial_t h + (v_i \partial_i) h$  in Eq. (1).

### Field-theoretic reformulation

### (3)

(2)

Stochastic problem (1) is equivalent to field theory with an increased number of fields {h, h', v<sub>i</sub>} and action functional S(Φ) = S<sub>h</sub>(Φ) + S<sub>v</sub>(Φ)
 [6], where

$$S_{h}(\Phi) = \frac{1}{2}h'D_{0}h' + h'\{-\nabla_{t}h + \varkappa_{0}\partial^{2}h + \frac{1}{2}(\partial h)^{2}\},$$

$$S_{v}(\Phi) = -\frac{1}{2}\int dt \int d\mathbf{x} \int d\mathbf{x}' v_{i}(t,\mathbf{x})D_{ij}^{-1}(\mathbf{x}-\mathbf{x}')v_{j}(t,\mathbf{x}').$$
(4)

■ Here  $D_{ij}^{-1}(\mathbf{x} - \mathbf{x}')$  is the kernel of the inverse operator  $D_{ij}^{-1}$  for integral operator from Eq. (3); integrations over (x, t) are implied in expression for  $S_h(\Phi)$ .

- Coordinates of fixed points of RG equations were calculated in one-loop approximation.
- The most realistic values of parameters ( $d=3, 2, 1, \xi=4/3 K$ olmogorov turbulence) correspond to the fixed point  $g^* = -\varepsilon$ ,  $w^* = 0, x^* = -8\xi/3$ .

### References

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